

**1st results of the MICROSCOPE test
of the equivalence principle in
space.**

Manuel RODRIGUES

On behalf of the MICROSCOPE team

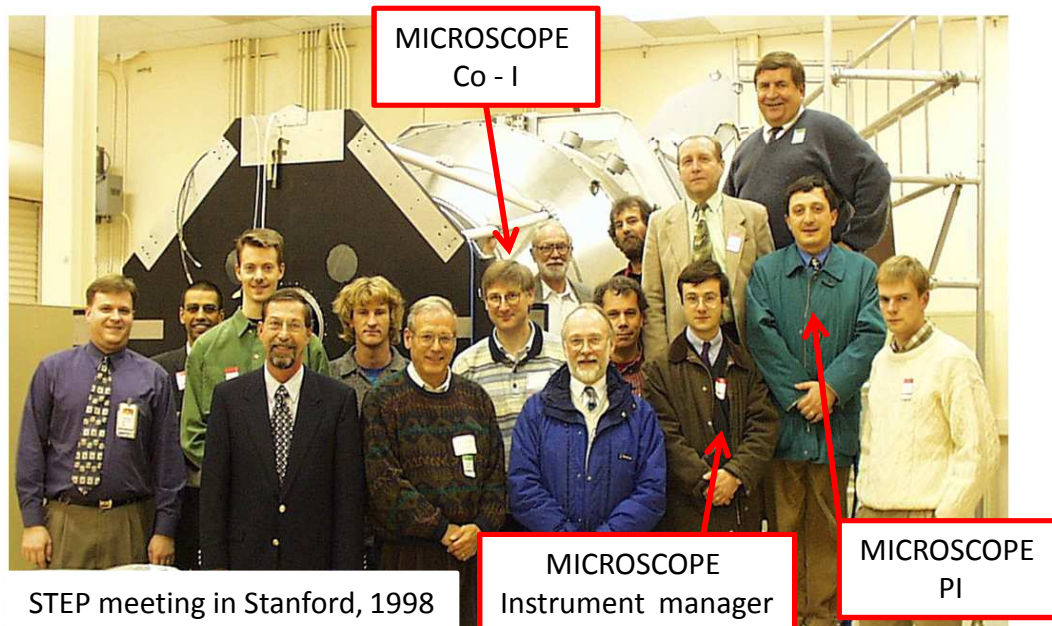


ONERA

THE FRENCH AEROSPACE LAB

STEP : THE MICROSCOPE ORIGINS

- ❖ Pr. Francis Everitt : PI of GPB & STEP had been gathering US & European teams in the late 90's => but no mission came up in NASA nor in ESA
- ❖ Stanford University : test of EP with 10^{-18} accuracy based on GPB technology

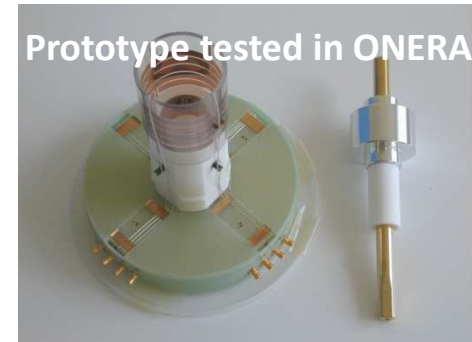
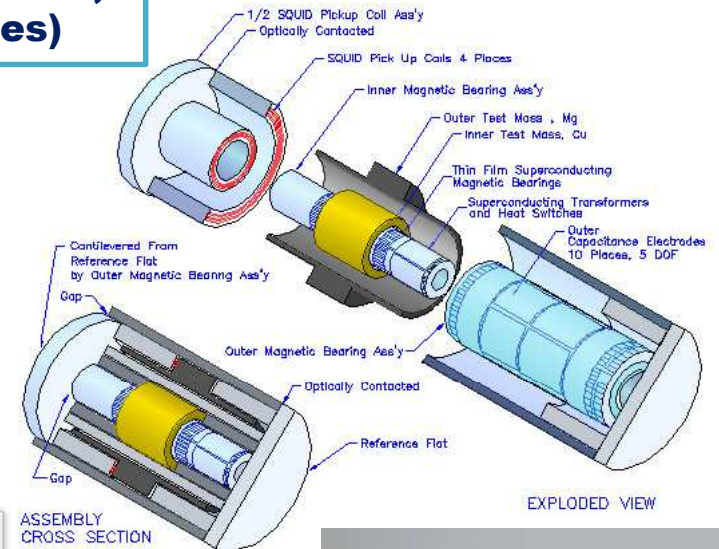
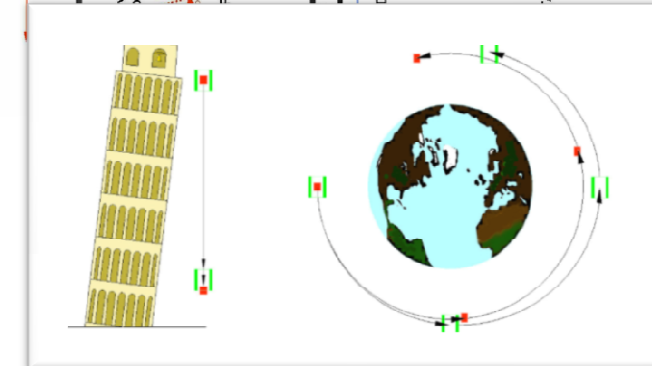
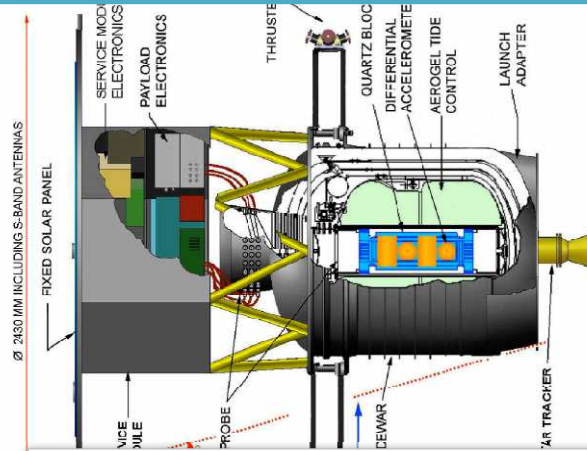


STEP MISSION AND ACCELEROMETER (Cryogenic tech., SQUIDS, Superfluid He, supraconducting test-masses)

STEP ACCELEROMETER CONCEPT

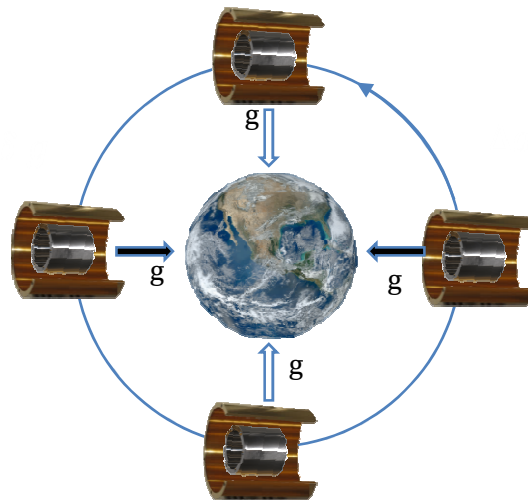


10-18



Prototype tested in ONERA

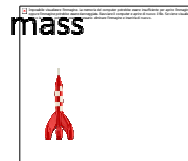
The « free-fall » test in space with MICROSCOPE resolution objective on $\delta : 10^{-15}$



$$g(@710km) = 7.9m/s^2$$

$$\Delta a = a1 - a2 = \left(\frac{m_{g1}}{m_{i1}} - \frac{m_{g2}}{m_{i2}} \right) g$$

m_g = gravitational mass



m_i = inertial mass



Comparison of the 2 body free-fall \leftrightarrow comparison of their acceleration:

$$\delta = \frac{a1 - a2}{\frac{1}{2}(a1 + a2)} = \frac{\frac{m_{g1}}{m_{i1}} - \frac{m_{g2}}{m_{i2}}}{\frac{1}{2} \left(\frac{m_{g1}}{m_{i1}} + \frac{m_{g2}}{m_{i2}} \right)}$$

If $\delta = 0$: $\Delta a = 0$

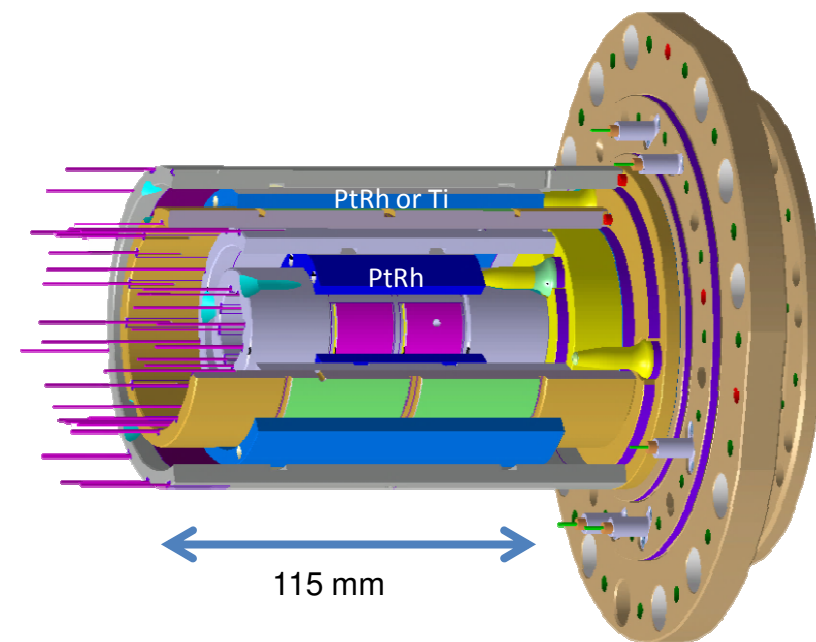
If $\delta \neq 0$: $\Delta a \neq 0$ detection of a signal collinear to g
(same phase, same frequency)

2 double accelerometers for the test

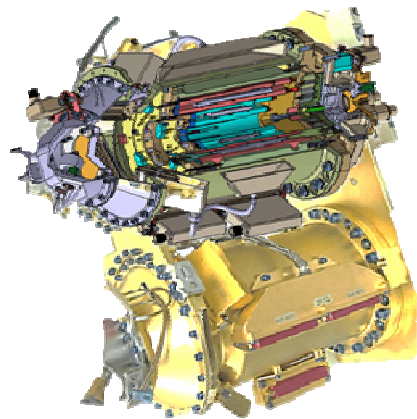
2 similar instruments on board which comprise each 2 concentric test-masses

SUEP : Sensor Unit with Ti / PtRh

SUREF : Sensor Unit with PtRh / PtRh



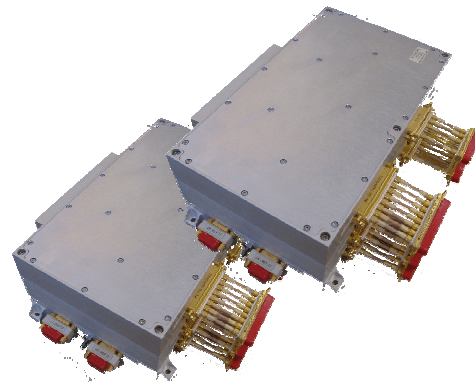
T-SAGE (Twin Space Accelerometer for Gravitation Experiment) – micrometer & microvolt accuracy inherited from GOCE, GRACE ONERA know how



Sensors: **SU PE + SU REF**

2 double-accelerometers

Each SU gives a TM difference of
acceleration to femto-g level



Analog Front End Electronics :
1 FEEU for each SU

Low Noise voltage references
 $0.2\mu\text{V Hz}^{-1/2}$

Low noise measurement
pick-up $<1\mu\text{V Hz}^{-1/2}$



Digital Interface Electronics:
2 stacked ICU

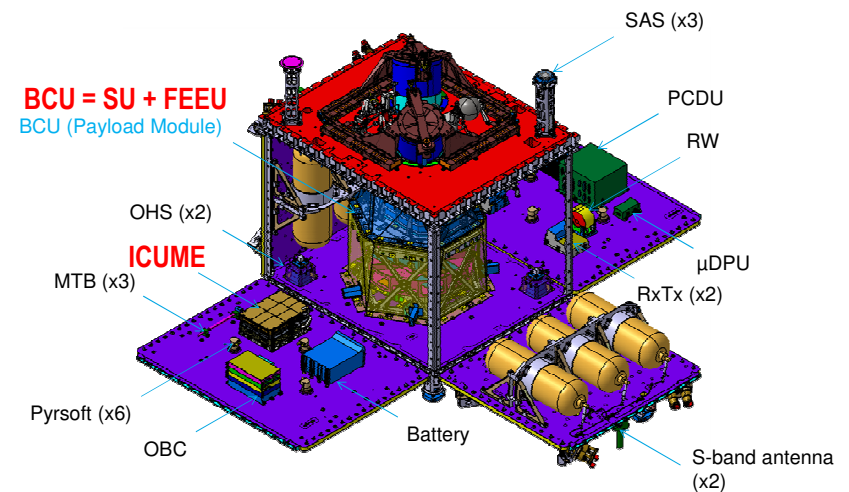
DSP + FPGA
Control loop handling
2x 24 x 40bits signals @ 1kHz

Science TM = 24bits @ 4Hz

The MICROSCOPE satellite




- ❖ Sun-synchronous polar orbit @ 710 km
- ❖ Several modes :
 - Inertial $f_{EP} = \text{orbital frequency} = 1.7 \times 10^{-4}$ Hz
 - 2 rotation rates of S/C
 - $f_{EP} = 0.9 \times 10^{-3}$ Hz & $f_{EP} = 3.1 \times 10^{-3}$ Hz

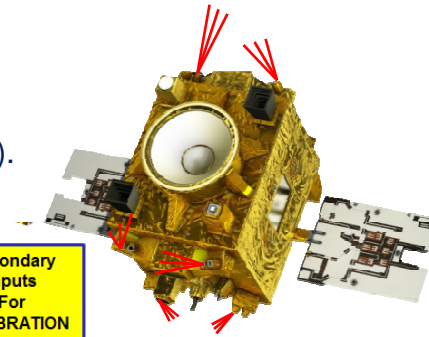
- ❖ Cold Gaz propulsion
- ❖ A space laboratory of 300kg
- ❖ 1,4 m x 1 m x 1,5 m
- ❖ Instrument in the BCU (Payload Thermal Cocoon Case) at the center of the satellite



DRAG-FREE SATELLITE LABORATORY OF PHYSICS

With capabilities of stimuli production:

-  ➤ linear or angular sine accelerations,
-  ➤ Test-masses displacements,
-  ➤ controlled thermal heaters (Off in science mode).



Performance of drag-free

$$\Gamma(f_{EP}) < 3 \times 10^{-13} \text{ m/s}^2$$

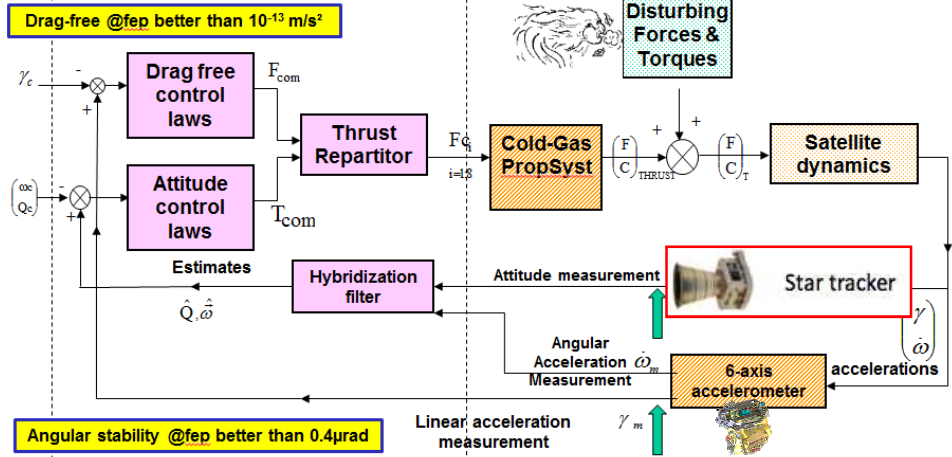
$$\dot{\Omega}(f_{EP}) < 4 \times 10^{-12} \text{ rd/s}^2$$

$$\Omega(f_{EP}) < 3 \times 10^{-10} \text{ rd/s}$$

$$\int \Omega < 1 \mu\text{rd}$$

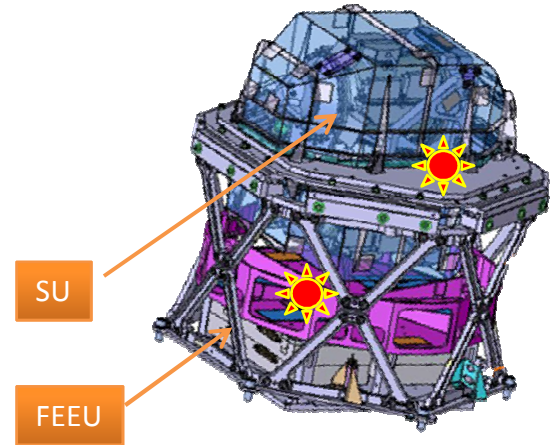
Bandwidths: 12 SU control loops (1Hz) + 6 DFACS loop (0.1Hz)
+ 8 thruster loop (10Hz)

MCA software : 4Hz measure sampling rate



Drag-free @fep better than 10^{-13} m/s^2

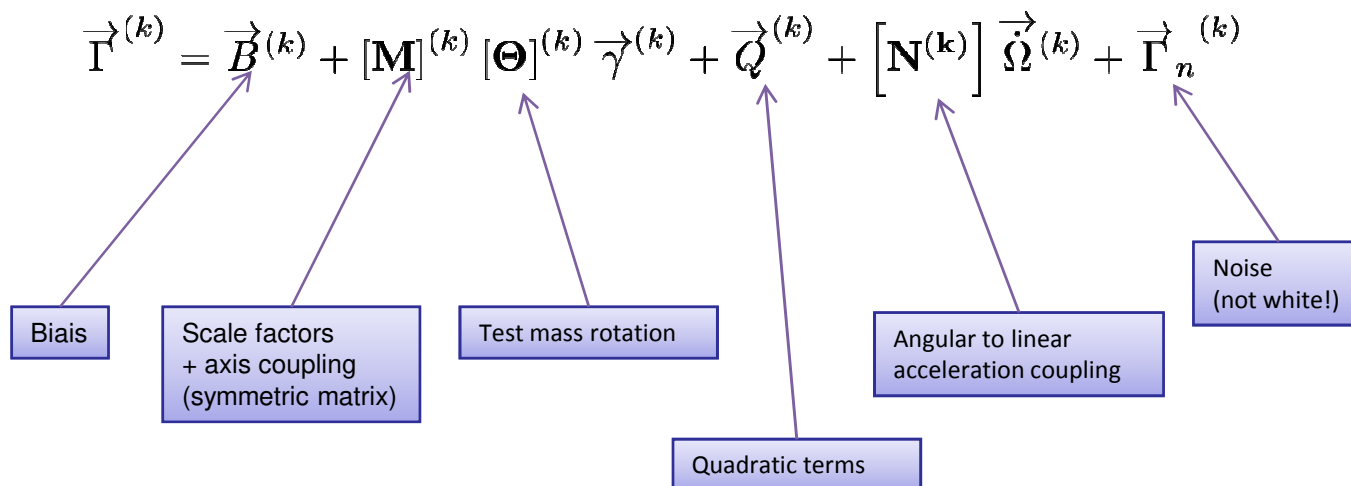
Angular stability @fep better than $0.4 \mu\text{rad}$



ACCELEROMETER MEASUREMENT

- sensor (test mass) k
- theoretical acceleration (input): $\vec{\gamma}^{(k)}$
- measured acceleration (output): $\vec{\Gamma}^{(k)}$

Contains the Eötvös parameter



The measure along the cylinder axis (X) = the main measure

$$2\Gamma_x^{(d)} = 2B_x^{(d)}$$

$$g = 7,9 \text{ ms}^{-2}$$

$$+ \delta_x g_x$$

$$+ \Delta_x S_{xx} + \Delta_y S_{xy} + \Delta_z S_{xz} + (ac_{13}\Delta_y + ac_{12}\Delta_z)S_{yz} + ac_{12}\Delta_y S_{yy} + ac_{13}\Delta_z S_{zz}$$

$$+ (-ac_{13}\Delta_y + ac_{12}\Delta_z + 2nd_{11})\dot{\Omega}_x - (\Delta_z - 2ac_{13}\Delta_x + 2nd_{12})\dot{\Omega}_y + (\Delta_y - 2ac_{12}\Delta_x + 2nd_{13})\dot{\Omega}_z$$

$$+ 2(-ac_{13}\dot{\Delta}_y + ac_{12}\dot{\Delta}_z)\Omega_x - 2(\dot{\Delta}_z - 2ac_{13}\dot{\Delta}_x)\Omega_y + 2(\dot{\Delta}_y - 2ac_{12}\dot{\Delta}_x)\Omega_z$$

$$+ mc_{11}\ddot{\Delta}_{x,inst} - mc_{12}\ddot{\Delta}_{y,inst} - mc_{13}\ddot{\Delta}_{z,inst}$$

$$+ 2(ad_{11}\Gamma_x^{(c)} + ad_{12}\Gamma_y^{(c)} + ad_{13}\Gamma_z^{(c)})$$

$$+ K_{2xx}^{(1)} \left(\frac{\Gamma_x^{(1)} - b_{0x}^{(1)}}{K_{1x}^{(1)}} \right)^2 - K_{2xx}^{(2)} \left(\frac{\Gamma_x^{(2)} - b_{0x}^{(2)}}{K_{1x}^{(2)}} \right)^2$$

+ noise

Eötvös parameter

estimated by calibration
observed or/and computed
negligible at Fep

Earth's gravity gradients
with test-mass off-centering Δ

ad_{11} : Scale factor matching
 $ad_{12 \text{ or } 13}$: Misalignment of 2 test-masses

$\dot{\Delta}$ and $\ddot{\Delta}$ are negligible in the bandwidth
of the test-mass servo loops

FIRST RESULTS PUBLISHED IN PRL BASED ON 2 SESSIONS

SUEP

	dateDebut	nomFiche	Num Orb	contrainte Environnement	crit.	duree	etat	conso GazZp	conso GazZm	capacite GazZp	capacite GazZm
206	2017-02-13T15:40:18.833216	CAL_K1dxDFIS1_01_SUEP	4322	NO_ECLIPSE_NO_LUNE	2	1.01295	E	0.7	1.1		
207	2017-02-14T00:02:44.983178		4327	NO_ECLIPSE_NO_LUNE	2	1.01295	E	0.5	0.6		
208	2017-02-14T01:43:07.970959	CAL_K1dxDFIS2_01_SUEP	4328	NO_ECLIPSE_NO_LUNE	2	5.07000	E	2.9	3.3	6579.4	6614.3
209	2017-02-14T10:05:34.128091		4333	NO_ECLIPSE_NO_LUNE	2	3.07939	E	10	9.3	6569.7	6604.9
210	2017-02-14T15:10:44.141758	EPR_V3DFIS2_01_SUEP	4334	NO_ECLIPSE_NO_LUNE	2	1.01295	E	6	151.3	6392.6	6453.3
211	2017-02-18T01:45:43.539435		4335	NO_ECLIPSE_NO_LUNE	2	1.01295	E	4.2	4.2	6386.9	6448.7
212	2017-02-18T04:15:53.554441	EPR_V3DFIS2_01_SUEP	4336	NO_ECLIPSE_NO_LUNE	2	1.01295	E	15	235.1	6123.1	6213.3
213	2017-02-23T09:55:00.000000		4337	NO_ECLIPSE_NO_LUNE	2	1.01295	E	0	0	6123.1	6213.3
214	2017-02-23T09:55:00.000000	TSNA	4338	NO_ECLIPSE_NO_LUNE	0	61.80639	E	0	3.3	6122.9	6209.7
215	2017-02-27T16:00:00.028541		4526	NO_ECLIPSE_NO_LUNE	2	1.01295	E	1.3	1.1	6121.7	6207.8
216	2017-02-27T17:40:23.014532	CAL_K1dxDFIS2_01_SUEP	4527	NO_ECLIPSE_NO_LUNE	2	5.07000	E	4.9	8.3	6116.9	6199.3
217	2017-02-28T02:02:49.160909		4532	NO_ECLIPSE_NO_LUNE	2	3.07939	E	10.4	11	6106.4	6187.8
218	2017-02-28T07:07:59.169132	EPR_V3DFIS2_01_SUEP	4535	NO_ECLIPSE_NO_LUNE	2	120.00000	E	384.8	405.8	5791	5781.7
219	2017-03-08T13:19:57.511429		4655	NO_ECLIPSE_NO_LUNE	2	2.57703	E	3.7	4.9	5716.8	5776.4
220	2017-03-08T17:35:20.494387	CAL_tetadZDFIS2_01_SUEP	4658	NO_ECLIPSE_NO_LUNE	2	5.07000	E	3.9	7.9	5712.9	5768.3
221	2017-03-09T01:57:46.642557		4663	NO_ECLIPSE_NO_LUNE	2	1.01295	E	0.8	1.4	5712.1	5766.8
222	2017-03-09T03:38:09.628548	CAL_tetadYDFIS2_01_SUEP	4664	NO_ECLIPSE_NO_LUNE	2	5.07000	E	3.6	8.3	5708.3	5758.3
223	2017-03-09T12:00:35.776718		4669	NO_ECLIPSE_NO_LUNE	2	1.18063	E	2.9	4	5705	5754
224	2017-03-09T13:5...										
225	2017-03-09T22:2...										
226	2017-03-10T00:1...										

$$\delta = [-1 \pm 9(stat) \pm 9(syst)] \times 10^{-15}$$

From mean square fit

Over 120 orbits

- Statistical noise integrated over 120 orbits
- Systematics evaluated with a majoring of SU temperature variations (15μK @ f_{EP})

Phys. Rev. Letts. 119 231101 (2017) : No evidence of violation > 1,9×10⁻¹⁴

SUREF

	dateDebut	nomFiche	Num Orb	contrainte Environnement	crit.	duree	etat	conso GazZp	conso GazZm	capacite GazZp	capacite GazZm
173	2017-01-18T14:22:59.978006		3944	NO_ECLIPSE_NO_LUNE	1	1.01295	E	0.9	0.9	6808.7	682
174	2017-01-18T16:03:22.968294	CAL_K1dxDFIS2_01_SUREF	3945	NO_ECLIPSE_NO_LUNE	1	5.07000	E	4.7	5.6	6804	682
175	2017-01-19T00:25:49.137973		3950	NO_ECLIPSE_NO_LUNE	1	3.07939	E	2.5	2.5	6801.2	6818
176	2017-01-19T05:30:59.159261	EPR_V2DFIS2_01_SUREF	3953	NO_ECLIPSE_NO_LUNE	1	120.00000	E	81.1	67.5	6720	6750.3
177	2017-01-27T11:42:57.925815		4073	NO_ECLIPSE_NO_LUNE	1	1.51531	E	1	0.6	6719	6749.6
178	2017-01-27T14:13:07.942964	EPR_V2DFIS2_01_SUREF	4074	NO_ECLIPSE_NO_LUNE	1	82.00000	E	56	48.4	6662.9	6701
179	2017-02-02T05:39:19.100109		4156	NO_ECLIPSE_NO_LUNE	1	2.57703	E	1.8	2	6661	6699
180	2017-02-02T09:54:42.094912	CAL_tetadZDFIS2_01_SUREF	4159	NO_ECLIPSE_NO_LUNE	1	5.07000	E	3.1	2.8	6657.8	6696.2
181	2017-02-02T18:17:08.262799		4164	NO_ECLIPSE_NO_LUNE	1	1.01295	E	0.6	0.7	6657.2	6695.5
182	2017-02-02T19:57:31.253445	CAL_tetadYDFIS2_01_SUREF	4165	NO_ECLIPSE_NO_LUNE	1	5.07000	E	2.6	3.1	6654.6	6692.4
183	2017-02-03T04:19:57.421332		4170	NO_ECLIPSE_NO_LUNE	1	1.18063	E	3.9	3.6	6650.5	6688.3
184	2017-02-03T06:16:57.435594	CAL_deltaYDFIS2_01_SUREF	4171	NO_ECLIPSE_NO_LUNE	1	5.07000	E	13.2	13.5	6637.1	6674.5
185	2017-02-03T14:39:23.605273		4176	NO_ECLIPSE_NO_LUNE	1	1.18365	E	0.4	0.6	6636.6	6673.8
186	2017-02-03T16:36:41.576425	CAL_K21xx_02_SUREF	4178	NO_ECLIPSE_NO_LUNE	1	10.00000	E	5.1	5.3	6631.4	6668.5

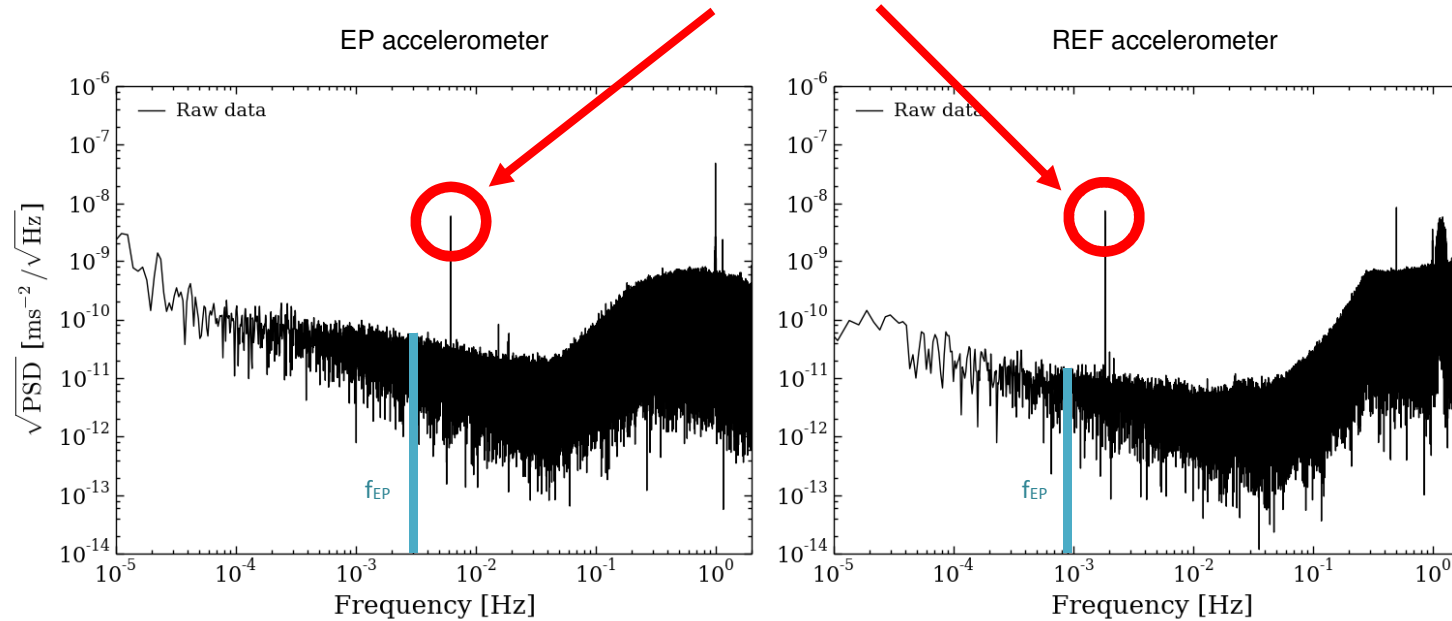
$$\delta = [+4 \pm 4(stat)] \times 10^{-15}$$

Over 62 orbits

- Statistical noise integrated
- Systematics evaluated after PRL (TBC) with a majoring of SU temperature variations (30μK @ f_{EP})

These 2 sessions represents 7% of available data for the EP test :
We well detect the Earth's gravity gradient effect but no violation...

Gravity gradient effect: due to an offcentring of the test-mass (<30μm)

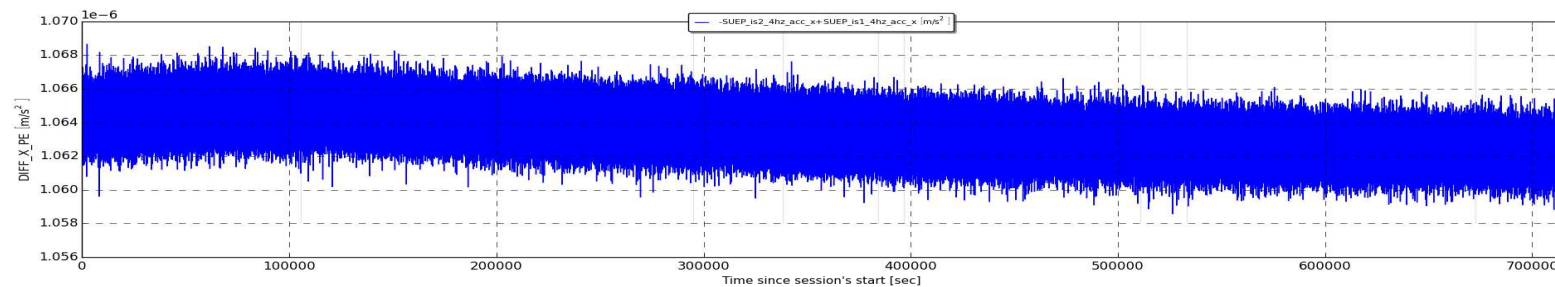


$$f_{EP} = 3.11 \times 10^{-3} \text{ Hz}$$

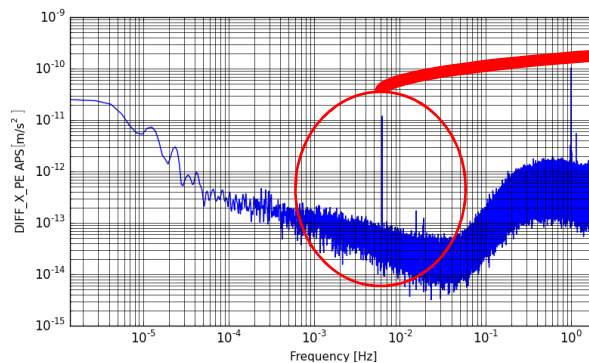
$$f_{EP} = 0.93 \times 10^{-3} \text{ Hz}$$

Effect of in-flight calibration on session 218 (SUEP)

- ❖ Time evolution of measured difference of acceleration on SUEP along X



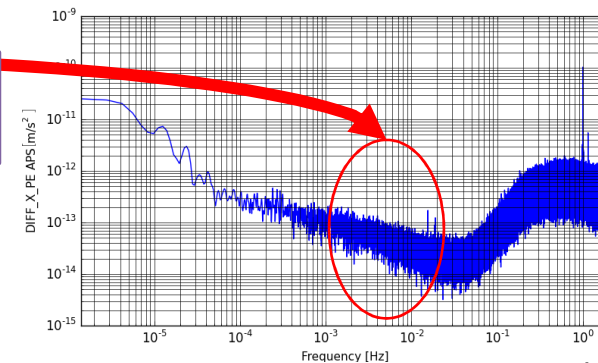
- ❖ Test-mass off-centering estimated through the Earth's gravity effect at $2f_{EP}$
=> Correction of off-centering effects at f_{EP} and $2f_{EP}$



$$\Delta x = (20.15 \pm 0.03) \mu\text{m}$$

$$\Delta z = (-5.69 \pm 0.03) \mu\text{m}$$

Level of acceleration to be corrected @ $f_{EP} < 3 \times 10^{-17} \text{m/s}^2$
NEGLIGIBLE for a rotating satellite

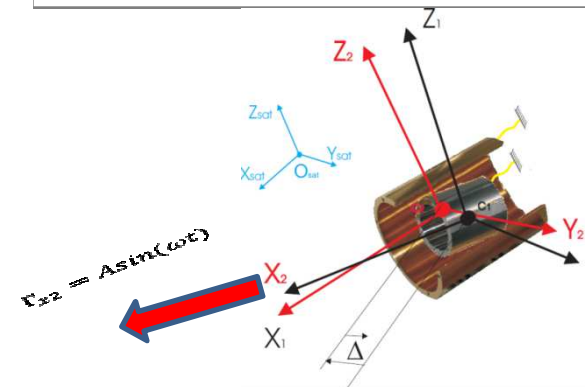
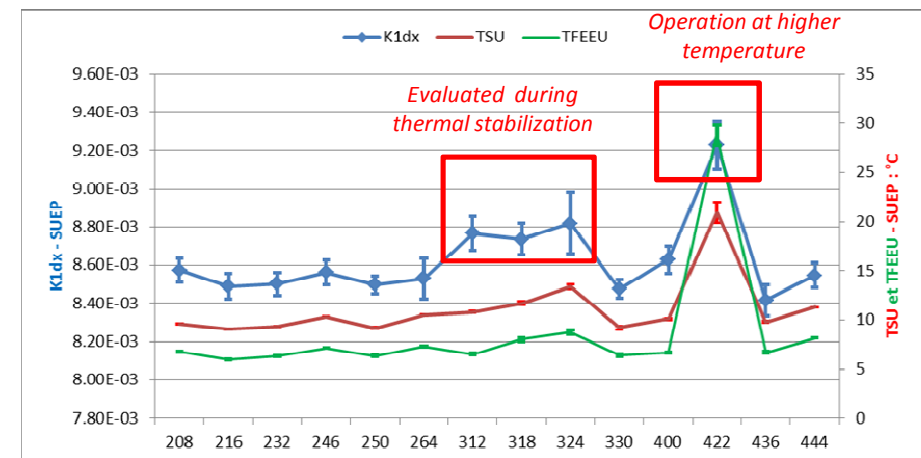


Calibration of scale factor matching

- ❖ Scale factor matching
- ❖ Evaluated by biasing the X mean acceleration measure output to the DFACS: $5 \times 10^{-8} \text{m/s}^2$ at $1.23 \times 10^{-3} \text{Hz}$
- ❖ Differential measure along X gives the scale factor matching error
- ❖ Level of DFACS residual disturbances @ f_{EP} :

$$K_{1dx} \Gamma_{cx}(f_{EP}) < 3 \times 10^{-15} \text{m/s}^2$$
 Gives a limit of 0.5×10^{-15} on δ

- Correction useful at 10^{-15} level
- Temperature effect correction not needed



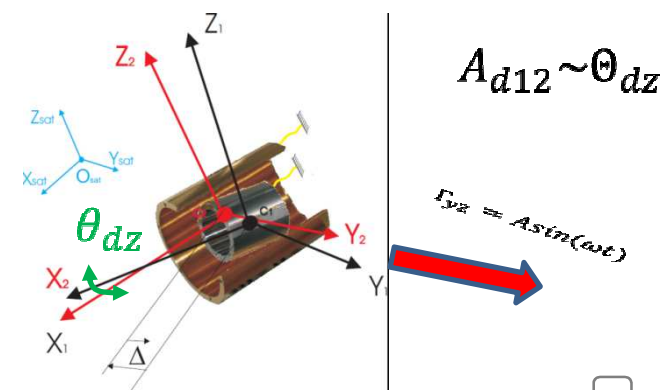
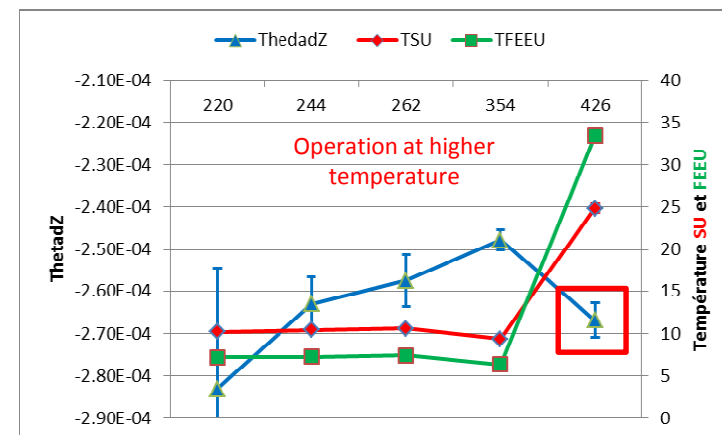
$$A_{d11} \sim K_{1dx}$$

Calibration of misalignment matching

❖ Misalignment of the 2 concentric test-masses

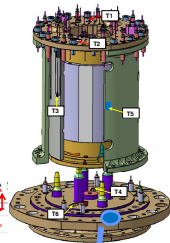
- ❖ Evaluated by biasing the Y mean acceleration measure output to the DFACS: $5 \times 10^{-8} \text{m/s}^2$ at $1.23 \times 10^{-3} \text{Hz}$
- ❖ Differential measure along X gives the misalignment about Z
- ❖ Level of DFACS residual disturbances @ f_{EP} :

- Correction NOT mandatory for a test at 10^{-15} level
- Temperature effect negligible

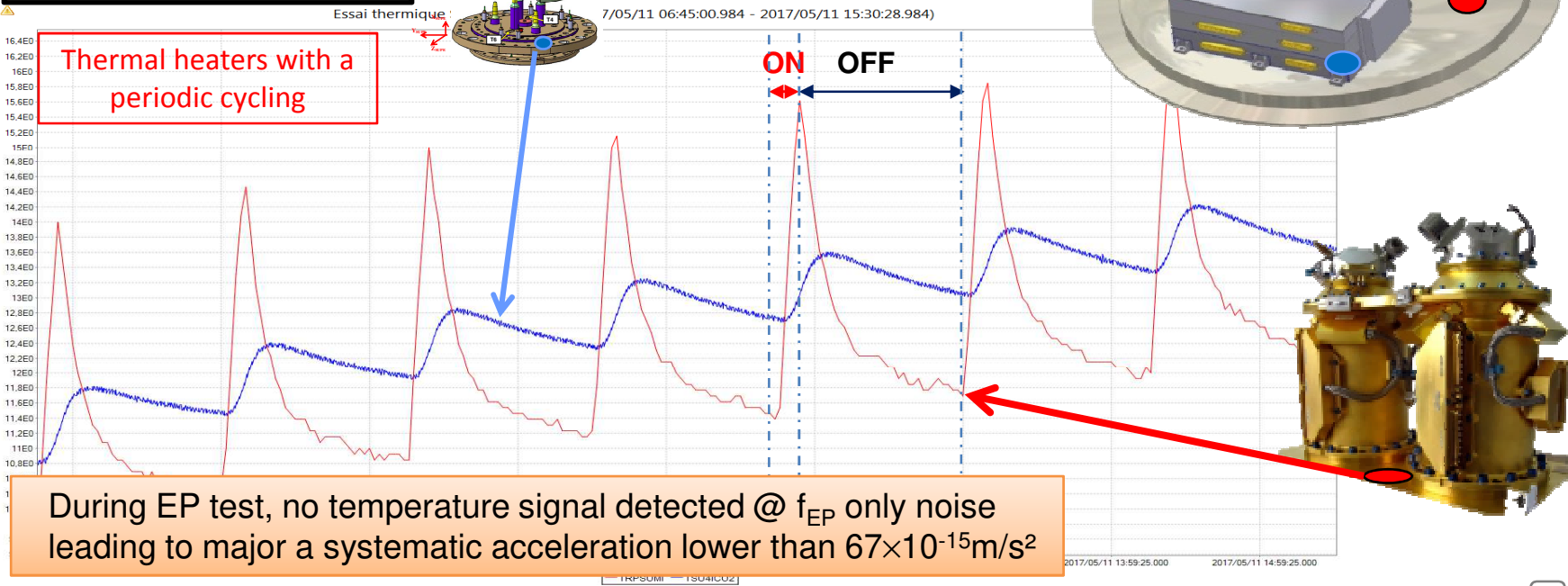
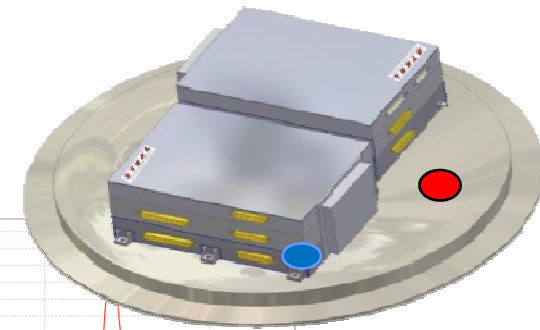


Thermal sensitivity measured in flight by local thermal stimuli

The ratio of differential acceleration to temperature variations @ heating frequency
=> thermal sensitivity of SU or FEEU



SU thermal probe at interface



Thermal heaters with a periodic cycling

During EP test, no temperature signal detected @ f_{EP} only noise leading to major a systematic acceleration lower than $67 \times 10^{-15} \text{m/s}^2$

CURRENT STATUS : in 2018 less science more sensitivity tests & technological tests

- ❖ 750 orbits dedicated to sensor thermic behavior and systematic check have been successfully performed => very promising
 - ❖ From March to August 2018: SUEP is to be continuously measuring without switch off (for technological experiment purposes)
 - ❖ In 2018 : more than 5 months of experiment dedicated to Aeronomy (Drag Free Off)
-
- ❖ EP test data available from the beginning : **1882 orbits** for SUEP and **932 orbits** for SUREF (including different temperature conditions & test-mass displacements) ; 300 orbits for calibration.
 - ❖ End of mission : 16th of October 2018

CONCLUSION

- ❖ **The satellite & the instrument have worked during more than 2 years in very good symbiosis, with outstanding performances.**

- ❖ **Analysis of less than 7% of the available data shows**
 - a factor 10 improvement on EP test experiments (PRL paper December 2017)
 - no violation at level of 1.9×10^{-14}

- ❖ **A lot of work remains:**
 - Effect of satellite cracks in the measurement : wavelet or shapelet modeling could improve the result
 - Thermal behavior of the SU core is being consolidated (improved analysis from PRL)
 - Better characterization of accelerometer along all axes (couplings, non linearity): better confidence on instrument physics modelisation
 - Process of all EP sessions to get a final result
 - **Publication of the final result foreseen at end of 2019**

- ❖ **Objective of the data process: get closer to the primary objective of 10^{-15} accuracy.**



TSAGE PAYLOAD TEAM - ONERA



S/C OPERATION – CNES ONERA



CENTER OF MICROSCOPE SCIENCE MISSION (CMSM) – ONERA+OCA

THANK YOU



Pierre Touboul (ONERA)
Prime Investigator



Gilles Metris (CNRS-UCA-OCA-Géoazur)
Co PI – Data analysis



Manuel Rodrigues (ONERA)
Co-I – Instrument + CMSM



Pierre-Yves Guidotti (CNES)
MICROSCOPE Proj. Manager



Alain Robert (CNES)
Perf. Group